

## Contents

- 347** Trajectory tracking control based on linear active disturbance rejection controller for 6-DOF robot manipulator  
*Qiao Guanyu(乔冠宇), Peng Cheng, Xu Zhenbang, Gao Huibin*
- 355** Single bitmap block truncation coding of color images using hill climbing algorithm  
*Zhang Lige(张力戈), Qin Xiaolin, Li Qing, Peng Haoyue, Hou Yu*
- 364** Fully-integrated ultra-wide band LNA in 0.18  $\mu\text{m}$  CMOS technology for 3 – 10 GHz applications  
*Du Jianchang(杜健昌), Fan Chen, Wang Zhigong, Xu Jian*
- 369** Outage performance of cognitive multisource multideestination relay networks with imperfect channel state information and interference from primary transmitter  
*Liu Shuai(刘帅), Sun Dechun, Liu Zujun, Yi Kechu, Yang Hong, Wang Kan*
- 378** Research on double differential pressure dynamic flowmeter  
*Liu Tao(刘涛), Zuo Zhibing, Yin Zhigang*
- 386** Assembly language and assembler for deep learning accelerators  
*Lan Huiying(兰慧盈), Wu Linyang, Han Dong, Du Zidong*
- 395** Heterogeneous coverage method with multiple unmanned aerial vehicle assisted sink nodes  
*Jin Shan(金杉), Jin Zhigang*
- 401** Brillouin scattering spectrum character extraction based on genetic algorithm and seeker optimization algorithm  
*Zhang Yanjun(张燕君), Jin Peijun, Fu Xinghu, Hou Jiaoru, Zhang Fangcao, Xu Jinrui*
- 408** Hopping planning of the bionic leg mechanism driven by PAMs with biarticular muscle  
*Chen Ziheng(陈子衡), Lei Jingtao, Cheng Liya, Gao Tongyue*
- 417** Optimizing deep learning inference on mobile devices with neural network accelerators  
*Zeng Xi(曾惜), Xu Yunlong, Zhi Tian*
- 426** Adaptive fuzzy compensation based composite nonlinear feedback controller design for robot manipulators  
*Jiang Yuan(蒋沅), Gong Chenglong, Dai Jiyang*
- 434** Research on static bearing characteristics of magnetic-liquid double suspension bearing  
*Zhao Jianhua(赵建华), Wang Qiang, Zhang Bin, Chen Tao, Gao Dianrong*
- 443** Wind disturbance rejection control based on the dynamic parameters estimation of quadrotors UAV  
*Yang Yanhua(杨艳华), Chen Yang*
- 452** Coordination control for crankshaft forging hydraulic press  
*Yao Jing(姚静), Li Yao, Cao Xiaoming, Sha Tong*
- 461** An empowerment evaluation framework for national scientific and technical information governance  
*Zhao Keran(赵柯然), Chen Meihua, Zeng Wen*